

Course code	Course name	L-T-P-Credits	Year of Introduction
AE407	DIGITAL CONTROL SYSTEM	3-0-0-3	2016
Prerequisite : AE301 Control system			
Course objectives			
<ul style="list-style-type: none"> To study the stability analysis of digital control system To equip the basic knowledge of digital process control design 			
Syllabus			
Discrete Data Control Systems - Signal conversion & processing - Z-transform- inverse Z-transform - Digital control systems- Pulse transfer function - Stability tests Frequency domain analysis of discrete systems - State space representation - Controllability and Observability -			
Expected outcome			
<ul style="list-style-type: none"> At the end of the semester Students will have knowledge of digital process control design. 			
Text Books			
<ol style="list-style-type: none"> B. C. Kuo , “<i>Digital control systems</i>” (Second Edition) , Oxford University Press, 2007 K. Ogatta, “<i>Discrete Time control systems</i> ”, 2nd ed. (PHI),1995 M. Gopal, “<i>Digital Control systems and state variable methods</i>”, Tata McGraw Hill. 			
Reference			
<ol style="list-style-type: none"> John Dorsey , “<i>Continuous & Discrete Control Systems</i> “, (MGH). Nagrath & Gopal , “<i>Control System Engineering</i>” (Wiley Eastern). 			
Course Plan			
Module	Contents	Hours	Semester Exam Marks
I	Introduction: Basic Elements of discrete data control systems, advantages of discrete data control systems, examples. Signal conversion & processing: Digital signals & coding, data conversion & quantization, sample and hold devices, Mathematical modeling of the sampling process; Data reconstruction and filtering of sampled signals: Zero order hold, first order Hold and polygonal hold.	6	15%
II	Review of Z transform. z transform and inverse z transform . Relationship between s- plane and z- plane- Difference equation . Solution by recursion and z- transform.	6	15%
FIRST INTERNAL EXAMINATION			
III	Digital control systems- Pulse transfer function . z transform analysis of closed loop open loop systems- Modified z- transfer function- Stability of linear digital control systems	8	20%
IV	Stability tests- Steady state error analysis- Root loci - Frequency domain analysis- Bode plots- Gain margin and	8	20%

	phase margin		
SECOND INTERNAL EXAMINATION			
V	Review of state space techniques to continuous data systems, state space representation of discrete time systems- Transfer function from state space model-various canonical forms- conversion of transfer function model to state space model-characteristics equation- solution to discrete state equations.	7	15%
VI	Controllability and Observability - Response between sampling instants using state variable approach-Pole placement using state feedback . Dynamic output feedback- Effects of finite wordlength on controllability and closed loop pole placement-	7	15%
END SEMESTER EXAMINATION			

QUESTION PAPER PATTERN:

Maximum Marks:100

Exam Duration: 3 Hours

Part A

Answer any two out of three questions uniformly covering Modules 1 and 2 together. Each question carries 15 marks and may have not more than four sub divisions.

(15 x 2 = 30 marks)

Part B

Answer any two out of three questions uniformly covering Modules 3 and 4 together. Each question carries 15 marks and may have not more than four sub divisions.

(15 x 2 = 30 marks)

Part C

Answer any two out of three questions uniformly covering Modules 5 and 6 together. Each question carries 15 marks and may have not more than four sub divisions.

(20 x 2 = 40 marks)