

Reg No.: _____

Name: _____

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY
SIXTH SEMESTER B.TECH DEGREE EXAMINATION(R&S), MAY 2019

Course Code: AE302
Course Name: PROCESS CONTROL

Max. Marks: 100

Duration: 3 Hours

PART A

Answer any two full questions, each carries 15 marks.

Marks

- | | | | |
|---|----|--|------|
| 1 | a) | With suitable example explain degrees of freedom | (10) |
| | b) | Enumerate the various incentives for process control. | (5) |
| 2 | a) | Explain the following terms | (5) |
| | | i)Steady state gain | |
| | | ii)Process time constant | |
| | b) | Analyse the following control loops | (10) |
| | | i)Liquid level control | |
| | | ii)Temperature control | |
| 3 | a) | What do you mean by self-regulating system and non-self-regulating system?
Explain. | (8) |
| | b) | Explain how an equal percentage valve compensates for non-linearity in the loop | (7) |

PART B

Answer any two full questions, each carries 15 marks.

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|---|----|---|------|
| 4 | a) | What are the various elements of a feedback control loop? | (10) |
| | b) | Distinguish servo control from regulator control. | (5) |
| 5 | a) | Explain Cascade control with example | (10) |
| | b) | Describe Ziegler Nichols method for controller tuning? | (5) |
| 6 | a) | What is feed forward control? Explain | (9) |
| | b) | Explain the various time integral performance criteria | (6) |

PART C

Answer any two full questions, each carries 20 marks.

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|---|----|--|------|
| 7 | a) | What is the principle of model predictive control? Explain | (10) |
| | b) | Explain the classification of artificial neural network? | (5) |
| | c) | Distinguish a crisp set from fuzzy set | (5) |

- 8 a) Illustrate process interaction in a multivariable system (12)
- b) Explain the following with reference to a multivariable system (8)
- i) Operating window
 - ii) Controllability
- 9 a) Explain step analysis method to find time constants and dead time for a second order model (10)
- b) How relative gain array can be used for loop pairing in a multivariable system (10)
