

Reg No.: _____

Name: _____

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY
SEVENTH SEMESTER B.TECH DEGREE EXAMINATION, DECEMBER 2018

Course Code: AE401
Course Name: LOGIC AND DISTRIBUTED CONTROL SYSTEM

Max. Marks: 100

Duration: 3 Hours

PART A*Answer any two full questions, each carries 15 marks.*

Marks

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| 1 | a) Explain in detail the architecture of PLC | (10) |
| | b) What is the need of isolators in PLC IO modules? Explain with block diagram indicating circuit details. | (5) |
| 2 | a) Explain IEC 61131 standard for PLC programming | (8) |
| | b) Draw the PLC ladder for Bottle filling system | (7) |
| 3 | a) With relevant figure explain analog and discrete I/O modules | (10) |
| | b) What are the advantages of PLC over relay logic | (5) |

PART B*Answer any two full questions, each carries 15 marks.*

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| 4 | a) With neat sketches, explain different types of displays in DCS systems | (10) |
| | b) Explain the role of DCS in industrial automation using automation pyramid | (5) |
| 5 | a) Explain the protocols used in the computer controlled systems and mention its standards. | (5) |
| | b) Explain the different configurations of Data Acquisition System. | (5) |
| | c) Write a short note on supervisory control. | (5) |
| 6 | a) Show how the following units are interfaced in SCADA system and explain the functions of each unit a) Human Machine interface unit b) Master Terminal unit c) Remote terminal unit. | (10) |
| | b) How an automation pyramid helps in industrial automation? | (5) |

PART C*Answer any two full questions, each carries 20 marks.*

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| 7 | a) Explain the hardware elements in high level operator interface in DCS? | (10) |
| | b) Explain the various record keeping function available with DCS | (5) |
| | c) Explain the modular packaging approach for providing high level operator interface in DCS? | (5) |
| 8 | a) Define risk. What are the commonly adapted risk terminologies? | (8) |
| | b) Illustrate safety life cycle with neat schematic. | (12) |
| 9 | a) Enumerate the design consideration for operator input used with high level operator interfaces in DCS | (10) |
| | b) Define the functions of safety instrumented system | (10) |
