systems

E192100

Reg No.:		D.: Name:	-
	ł	APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY FIFTH SEMESTER B.TECH DEGREE EXAMINATION(R&S), DECEMBER 2019	)
		Course Code: AE307 Course Name: SIGNALS AND SYSTEMS	
Μ	Max. Marks: 100 Duration:		Hours
		PART A Answer any two full questions, each carries 15 marks.	Marks
1	a)	Represent the sequence $x(n) = \{3, 2, -1, 6, 4, 1\}$ as sum of shifted scaled	(3)
		impulses, where $x(0) = 2$ . Also sketch the signal.	
	b)	Find whether the signal $x(t) = \begin{cases} t-2, -2 \le t \le 0\\ 2-t, & 0 \le t \le 2\\ 0 & Otherwise \end{cases}$ is energy or power signal.	(5)
		Also find the energy and power of the signal.	
	c)	Obtain the linear convolution of $x_1(t)$ and $x_2(t)$ , where $x_1(t) = t u(t)$ and	(7)
		$x_2(t) = e^{-2t}u(t)$ , where $u(t)$ represents the unit step signal.	
2	a)	Check whether or not the given system $y(t) = x(t-2) + x(2-t)$ is linear,	(5)
		time invariant, causal, memory less and stable, where $x(t)$ represents the input	
		and $y(t)$ represents the output.	
	b)	Find even and odd components of the following signals	(5)
		i. $x(t) = \cos(t) + \sin(t) + \cos(t)\sin(t)$	
		ii. $x(n) = \{-2, 1, 2 - 1, 3\}$ , where $x(0) = 2$	
	c)	Determine the step response of the system described by the difference equation	(5)
		$y[n] - \frac{1}{2}y[n-1] = x[n]$ for $n = 0,1,2,3,4$ where $x[n]$ represents the input and	
		y[n] represents the output. Initial condition $y[-1] = -2$	
3	a)	Find whether the following signals are stable or not if $x(t)$ represents input and	(5)
		y(t) represents output and $h(t)$ represents impulse response.	
		i. $y(t) = e^{x(t)}$ , where $ x(t)  \le 8$ ii. $h(t) = e^{2t}u(t)$	
		iii. $y(n) = \delta(n) + \frac{1}{2}\delta(n-1) + \frac{1}{4}\delta(n-2)$ iv. $h(n) = a^n$ for $0 < n < 11$	

v. h(t) = (t+5)u(t)b) Write short notes on differential and difference equation representation of LTI (5)

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Find the convolution between  $x(n) = 2^n u(n)$  and  $h(n) = \left(\frac{1}{2}\right)^n u(n)$ (5) c)

### PART B

## Answer any two full questions, each carries 15 marks.

- a) Explain the Hilbert transform and its properties in detail. (10)4
  - Find the Discrete Time Fourier Transform of  $x[n] = \begin{cases} 2^n, & 0 \le n \le 9\\ 0, & 0 \end{cases}$ (5) b)
- State and explain the sampling theorem and aliasing for band limited signals 5 (8)a) showing the sampled spectrum.
  - b) Explain the conditions for distortion less transmission through an LTI system (7)
- a) Using Fourier Transform, find the convolution of the signals  $x_1(t) = te^{-t}u(t)$ 6 (10)and  $x_2(t) = t e^{-2t} u(t)$ 
  - (5) One period of the DTFS coefficients of a signal is given by  $X[k] = \left(\frac{1}{2}\right)^k$  for b)
    - $0 \le k \le 9$ . Find the time domain signal x(n) by assuming N = 10.

## PART C

# Answer any two full questions, each carries 20 marks.

Determine the transfer function and the impulse response for the causal linear 7 a) (6)time-invariant system described by the differential equation using Laplace transform.

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = 2\frac{d}{dt}x(t) - 3x(t)$$
  
b) A system has the transfer function  $H(S) = \frac{3s-1}{s^2+5s-6}$ . (9)

- i. Find the impulse response of the system by assuming that the system is
  - a) Stable
  - b) Causal
- ii. Can this system be both stable and causal?
- c) Determine the initial and final values of the signal x(t) whose Laplace transform (5)

is 
$$X(S) = \frac{7s+10}{s(s+2)}$$

a) Find the difference equation description of the system with transfer function (4) 8  $H[Z] = \frac{5z+2}{z^2+3z+2}$ 

Find the inverse Z transform of  $X[z] = \frac{1 - z^{-1} + z^{-2}}{(1 - \frac{1}{2}z^{-1})(1 - 2z^{-1})(1 - z^{-1})}$ , if ROC is (8) b)

- i. 1 < |Z| < 2
- ii.  $\frac{1}{2} < |Z| < 1$

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- c) Determine the z transform and Region of Convergence (ROC) of the signal (8)  $x(n) = a^n u(n) - b^n u(-n-1)$
- 9 a) Determine the unit step response for the causal LTI system described by the (10) difference equation using Z-Transform.

$$y[n] = 7y[n-1] - 12y[n-2] + 2x[n] - x[n-2]$$

b) Determine the unit step response for the causal LTI system described by the (10) differential equation using Laplace Transform.

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = \frac{d}{dt}x(t) + 10x(t)$$
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